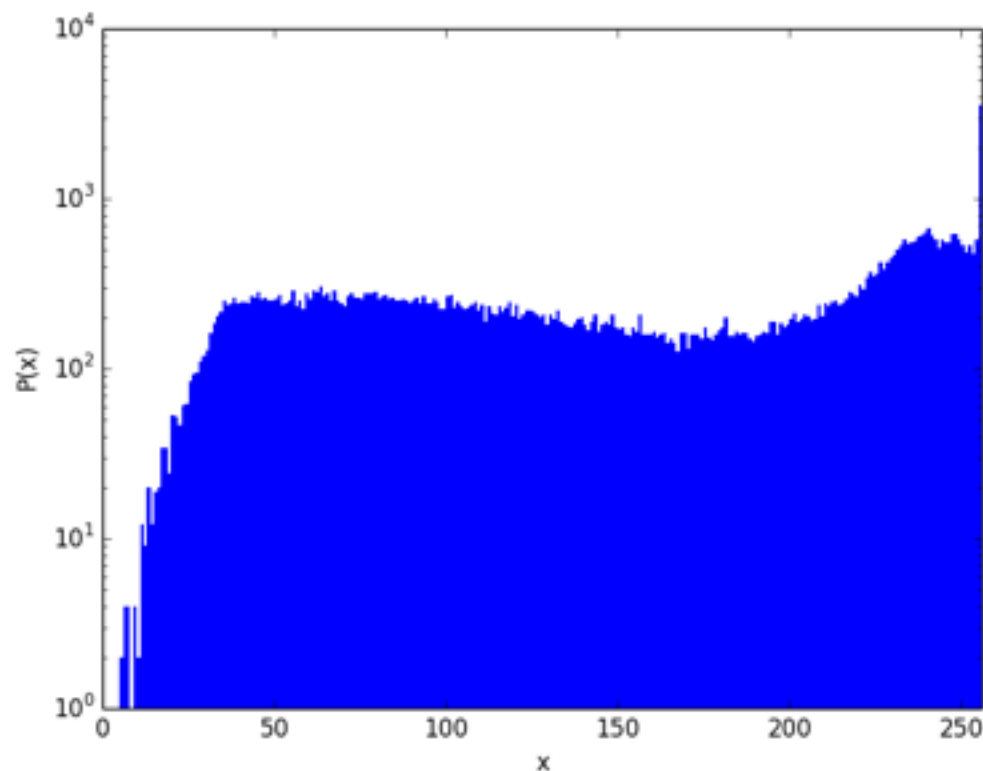


# Statistics & Bayesian Inference Lecture 1

Joe Zuntz



# Lecture 1

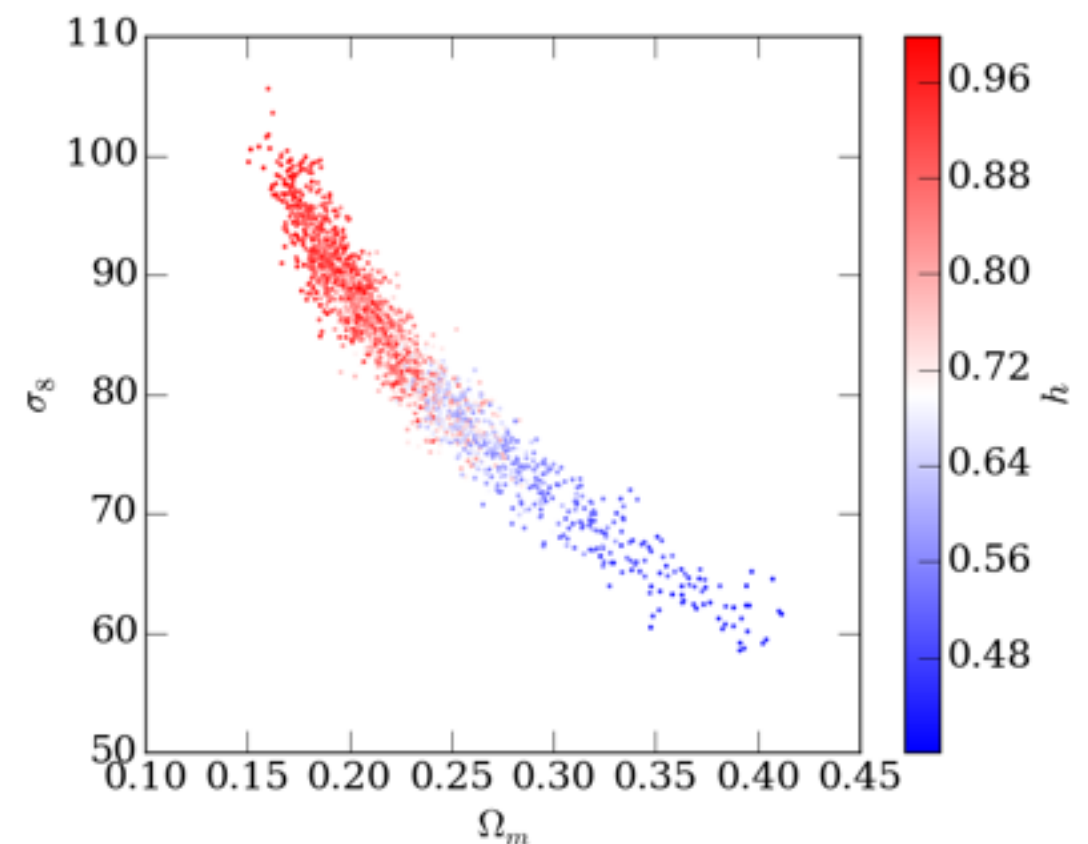
## Essentials of probability

- Motivations
- Definitions
- Probability Distributions
- Basic probability operations
- Some analytic distributions
- Bayes Theorem
- Models & Parameter Spaces
- How scientists can use probability

# Motivations

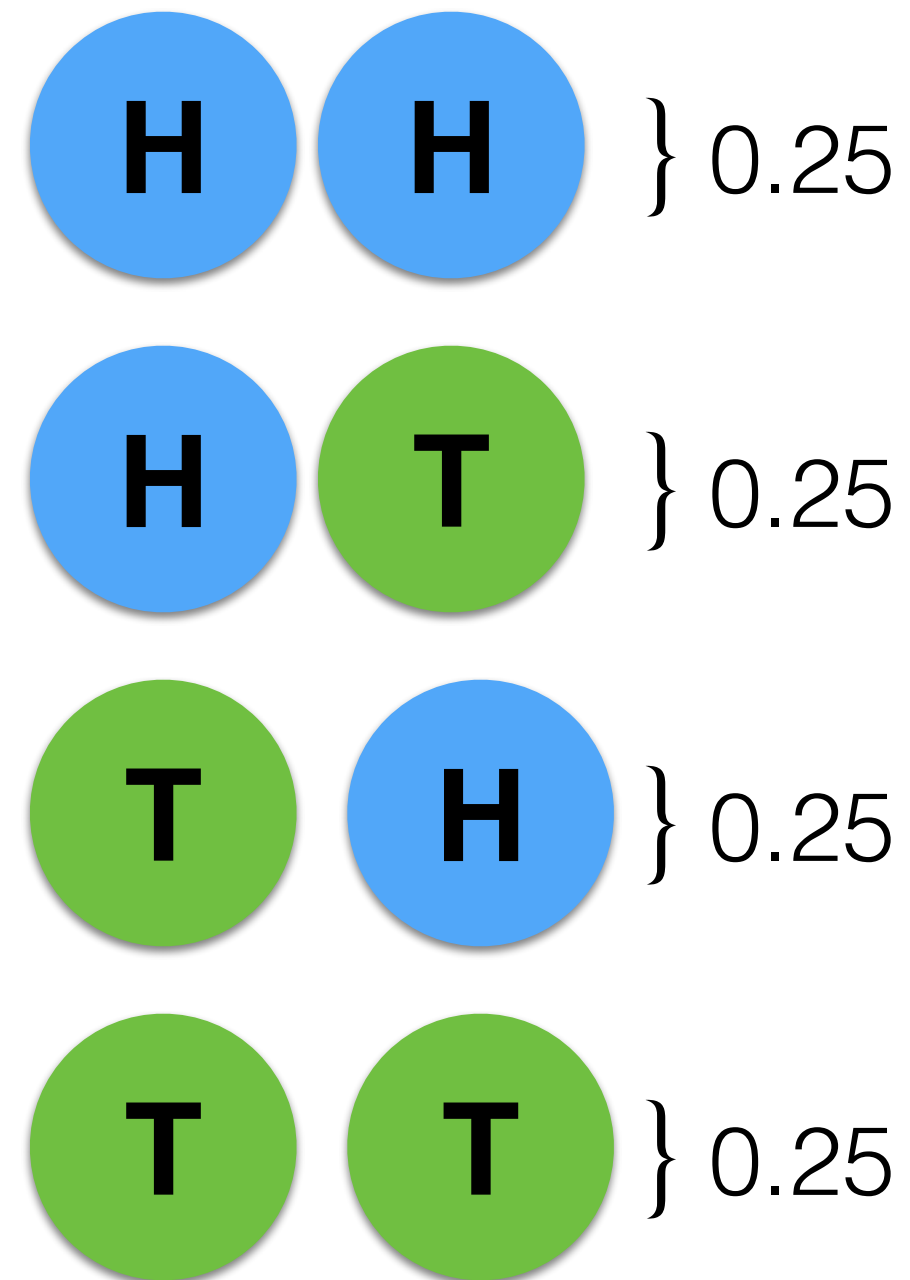
- Learn as much as possible from our (expensive) data
  - Constrain parameters in models
  - Test & compare models
- Characterize collections of numbers

$$H_0 = (72 \pm 8) \text{ km s}^{-1} \text{ Mpc}^{-1}$$



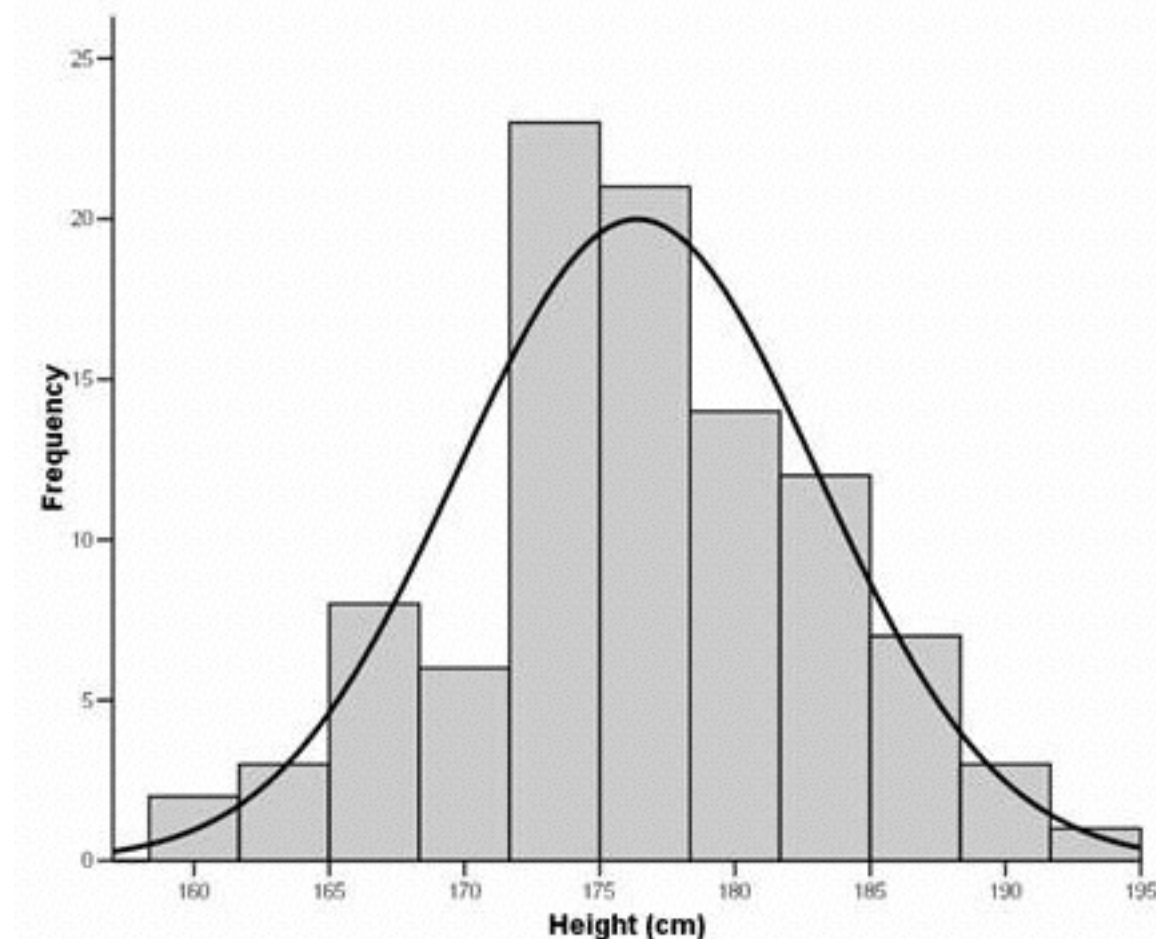
# Probability Distributions: Definitions

- Assign real number  $P \geq 0$  to each member of a *sample space* (discrete or continuous, finite or infinite)
- $P$ =probability density function (PDF) or probability mass function (PMF)
- This set represents possible outcomes of an experiment/game/event/situation
- e.g. possible results tossing two coins, height of next person to walk through door



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# Probability Distributions: Definitions

- A random variable  $X$  is any value subject to randomness, e.g.:
  - was first toss heads?  
was the sequence Heads-Tails?  
were both tosses the same?
- Discrete  $X$ :  $P$  is a list of values
- Continuous  $X$ :  $P$  is a function, PDF, (which we have to integrate to answer questions)

# Probability Distributions:

## Basic properties

- Since  $X$  must have exactly one value:

- Discrete: 
$$\sum_{x \in X} P(x) = 1$$

- Continuous: 
$$\int_{x \in X} P(x) dx = 1$$

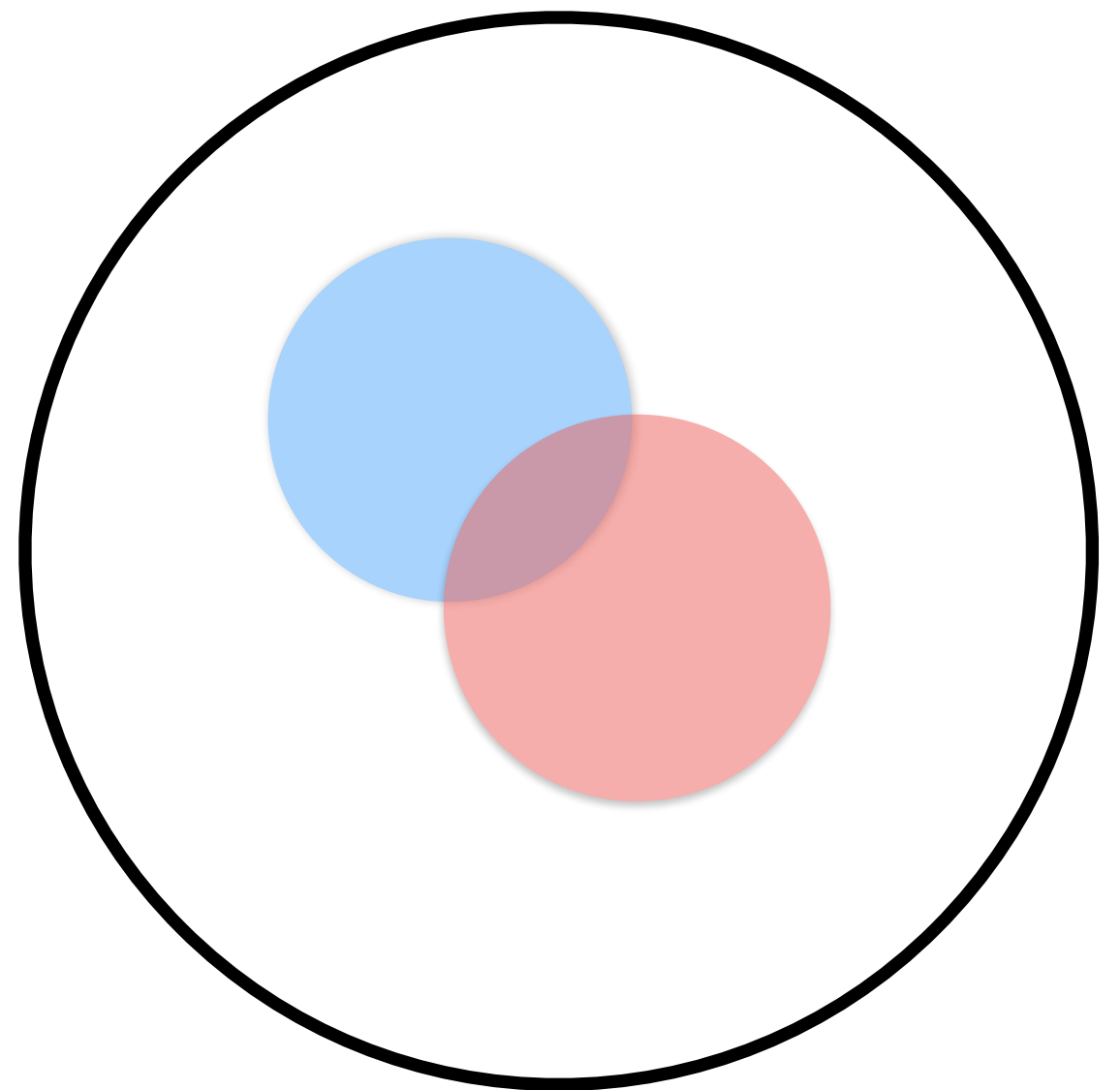
- $P(X=x) = f(x)$

Usually just write  $P(X) = f(x)$

- $0 \leq P(x) \leq 1$

# Probability Distributions: Combining Probabilities

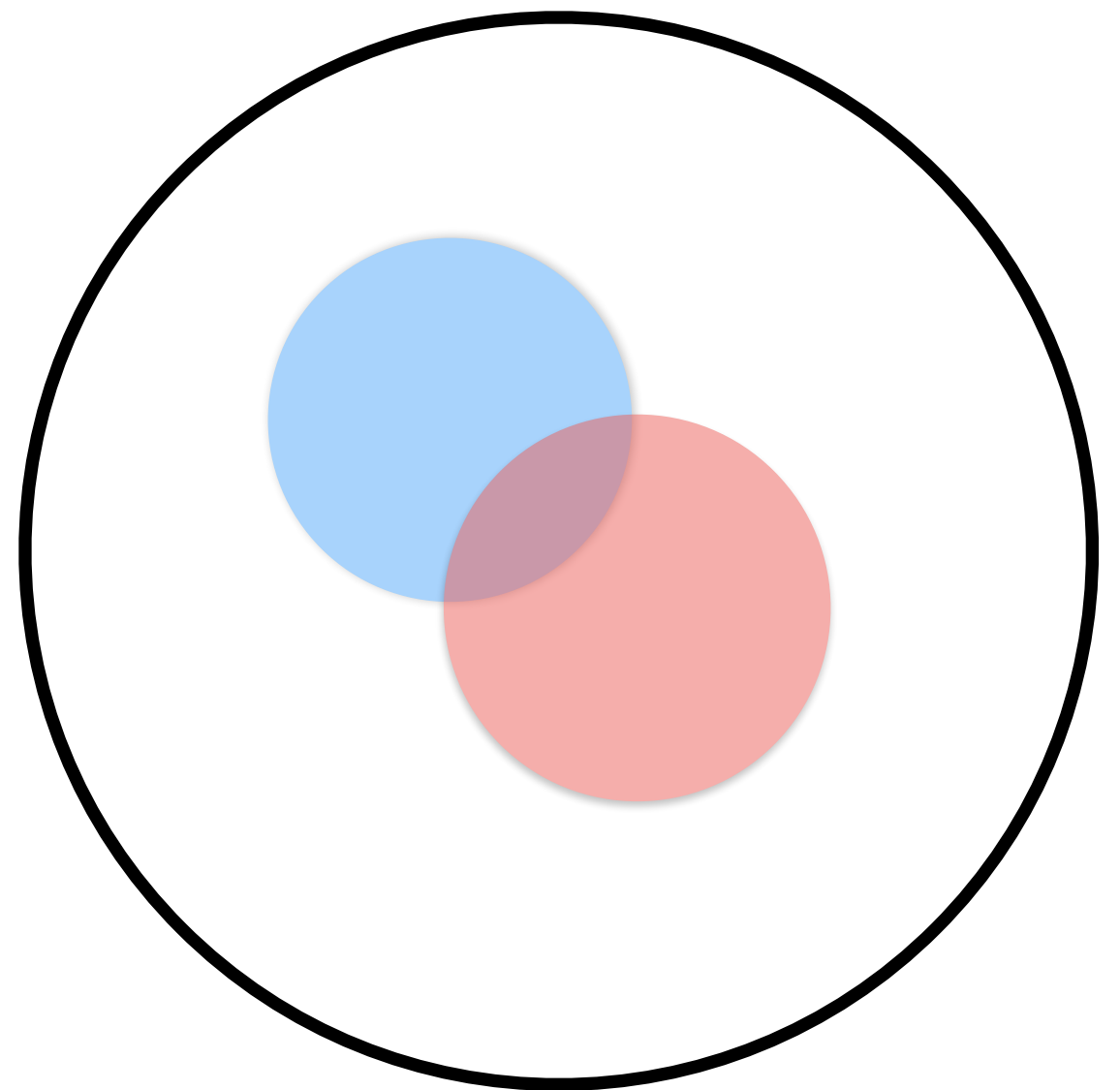
- Joint probability  
 $P(XY)$   
 $P(X=x \text{ and } Y=y)$   
 $P(X \cap Y)$
- Union  
 $P(X=x \text{ or } Y=y)$   
 $P(X \cup Y)$





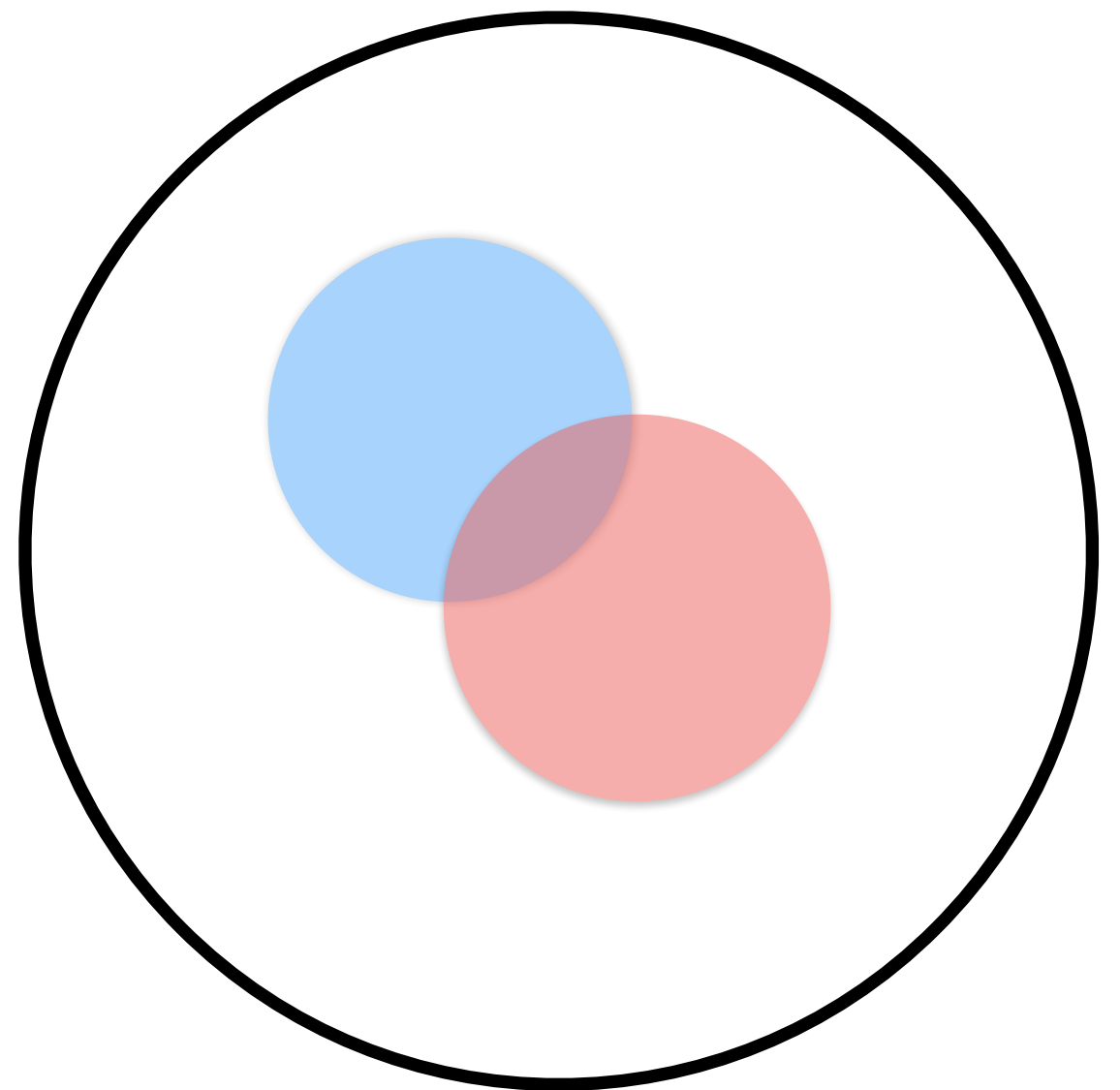
# Probability Distributions: Combining Probabilities

- Conditional  
 $P(X=x \text{ given } Y=y)$   
 $P(X|Y)$
- Independence:
  - $P(X|Y) = P(X)$
  - $X$  independent of  $Y$



# Probability Distributions: Identities

- $P(\text{not } X) = 1 - P(X)$
- $P(XY) = P(X|Y) P(Y)$
- $P(X \cup Y) = P(X) + P(Y) - P(X \cap Y)$



# Probability Distributions: Expectations

- The expectation (or mean) of a random variable  $X$  is given by:

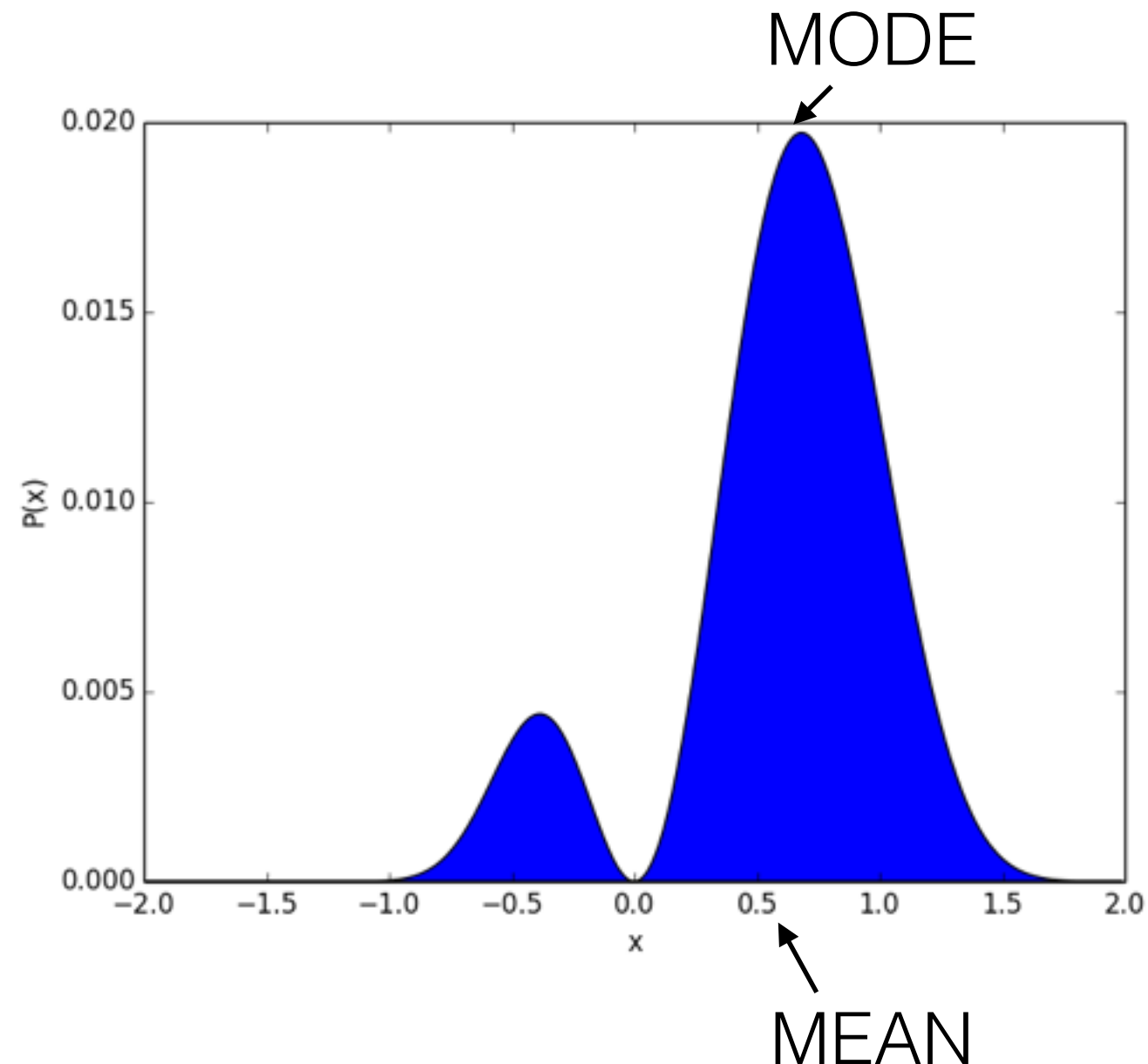
$$E(X) = \sum P(X)X \qquad E(X) = \int P(X)X dX$$

- Or a function of it by:

$$E(f(X)) = \sum P(X)f(X) \qquad E(f(X)) = \int P(X)f(X) dX$$

# Probability Distributions: Expectations

- Expectations are one measure of centrality, and not always a good one.
- Mode and median also exist
- All just ways of reducing or characterizing a distribution



# Probability Distributions: Marginalizing

- Discrete:

$$P(x) = \sum_i P(x|y_i)P(y_i)$$

- Continuous:

$$P(x) = \int P(x|y)P(y)dy$$

- If you don't care about something, marginalize over it

# Probability Distributions: Changing variables

- Probability mass must be conserved, not density
- Relate with a Jacobian
- Be especially careful in more dimensions

$$u = f(x)$$

$$P(u)du = P(x)dx$$

$$P(u) = P(x) \frac{dx}{du}$$

$$= P(x) / \frac{du}{dx}$$

$$= P(x) / f'(x)$$

# Probability Distributions: Drawing samples

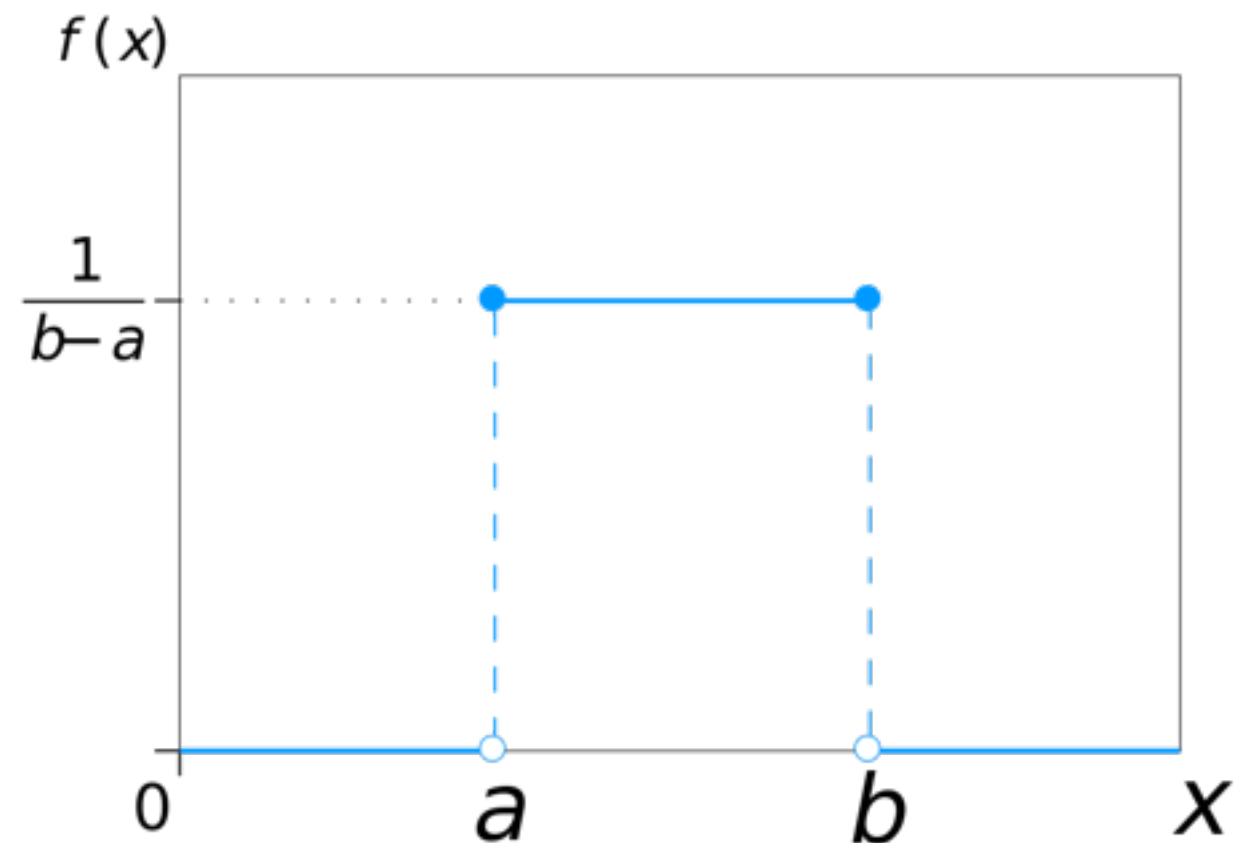
- Generate values of  $X$  with probability specified by  $P(X)$
- Draw enough samples: histogram looks like PDF
- See lecture 3

# Probability Distributions: Analytic examples

- Wikipedia is brilliant for this

- **Uniform**

- Delta function
- Gaussian (normal)
- Exponential
- Poisson

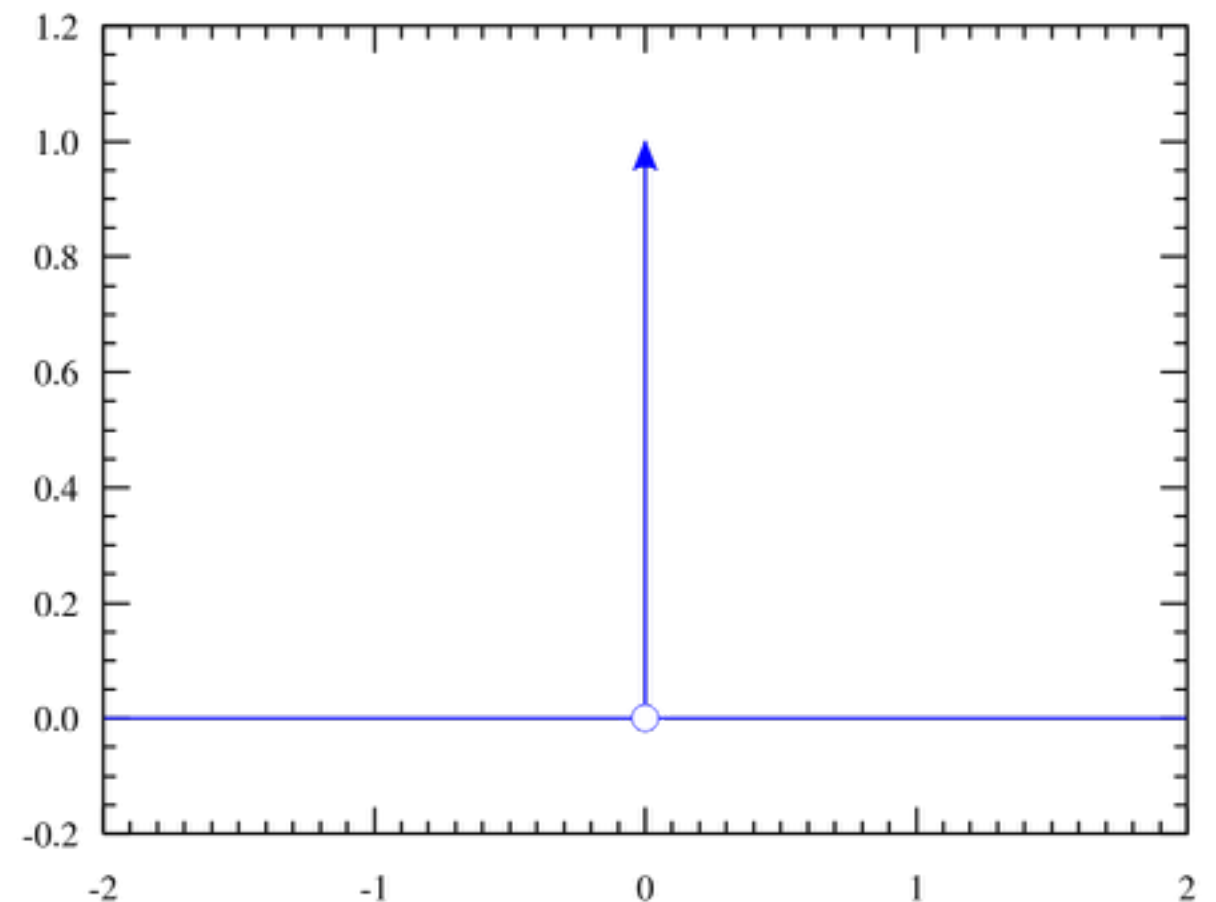


$$P(x) = \frac{1}{b-a}, \quad x \in [a, b]$$



# Probability Distributions: Analytic examples

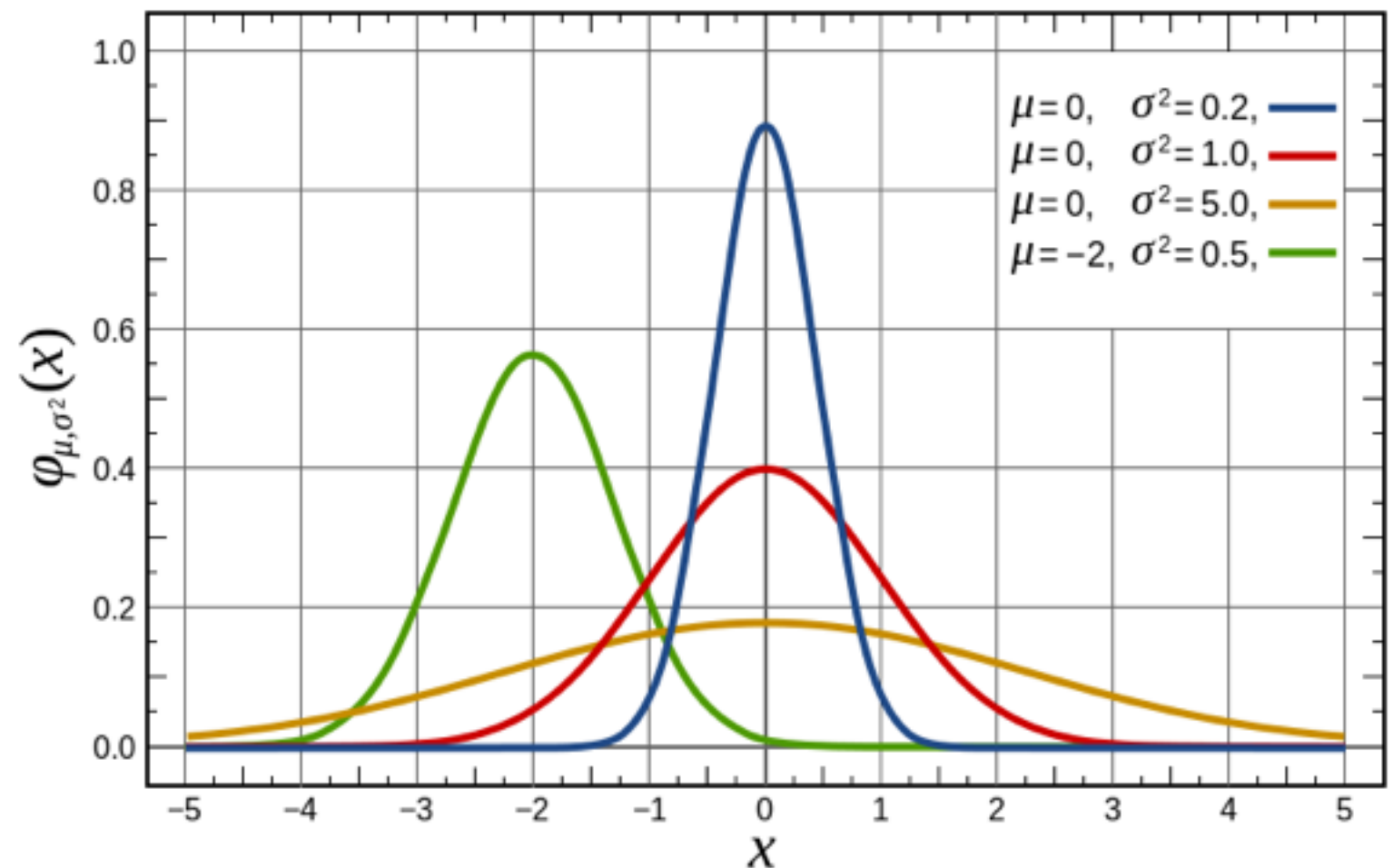
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$$P(x) = \delta(x - x_0)$$

# Probability Distributions: Analytic examples

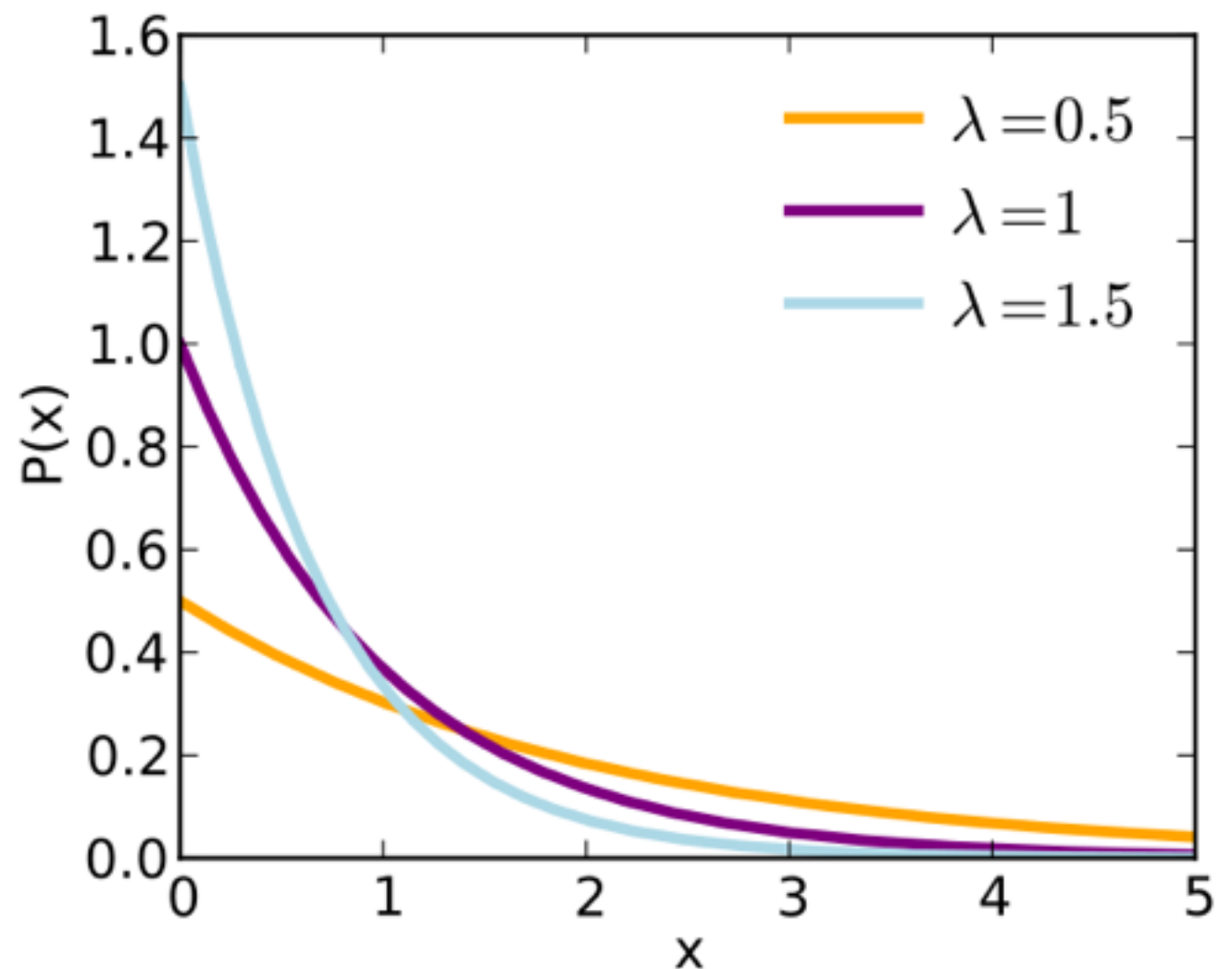
- Wikipedia is brilliant for this
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$$P(x) = \frac{1}{\sqrt{2\pi\sigma^2}} \exp -\frac{(x - \mu)^2}{2\sigma^2}$$

# Probability Distributions: Analytic examples

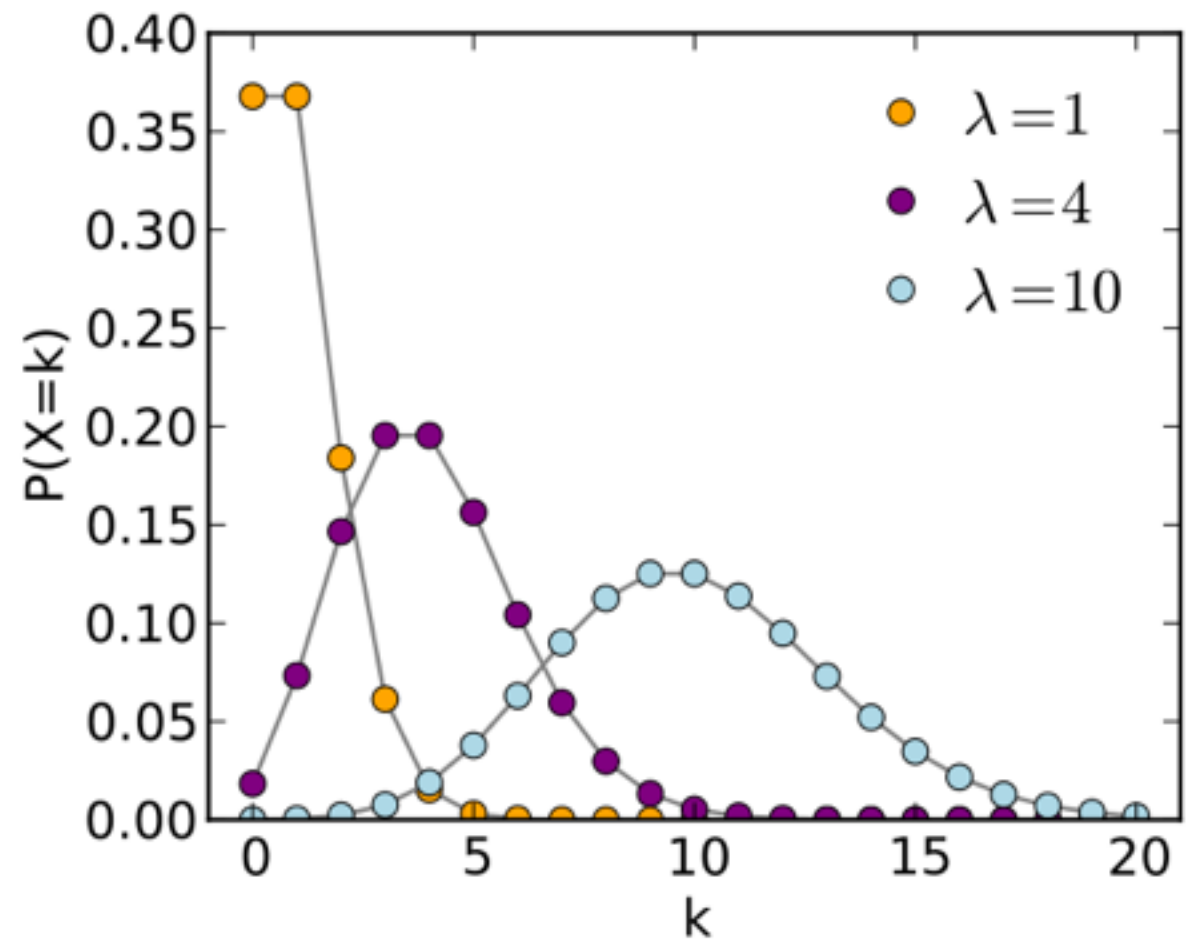
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- **Exponential**
- Poisson



$$P(x) = \lambda e^{-\lambda x}, \quad x > 0$$

# Probability Distributions: Analytic examples

- Wikipedia is brilliant for this
- Uniform
- Delta function
- Gaussian (normal)
- Exponential
- **Poisson**



$$P(n) = \frac{\lambda^n e^{-\lambda}}{n!}$$

# Bayes Theorem and Inference

$$\begin{aligned}P(AB) &= P(A|B)P(B) \\ &= P(B|A)P(A)\end{aligned}$$

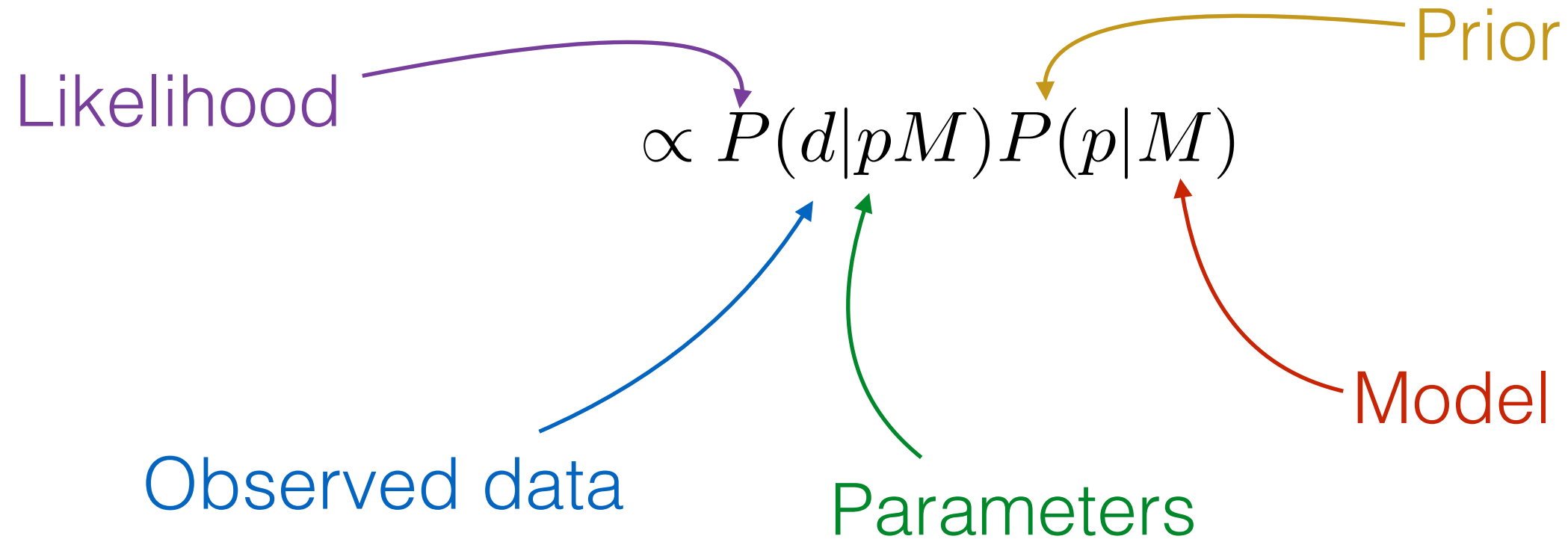
# Bayes Theorem and Inference

$$\begin{aligned}P(AB) &= P(A|B)P(B) \\ &= P(B|A)P(A)\end{aligned}$$

$$\therefore P(A|B) = \frac{P(B|A)P(A)}{P(B)}$$

# Bayes Theorem and Inference

$$P(p|dM) = \frac{P(d|pM)P(p|M)}{P(d|M)}$$



# Bayes Theorem and Inference

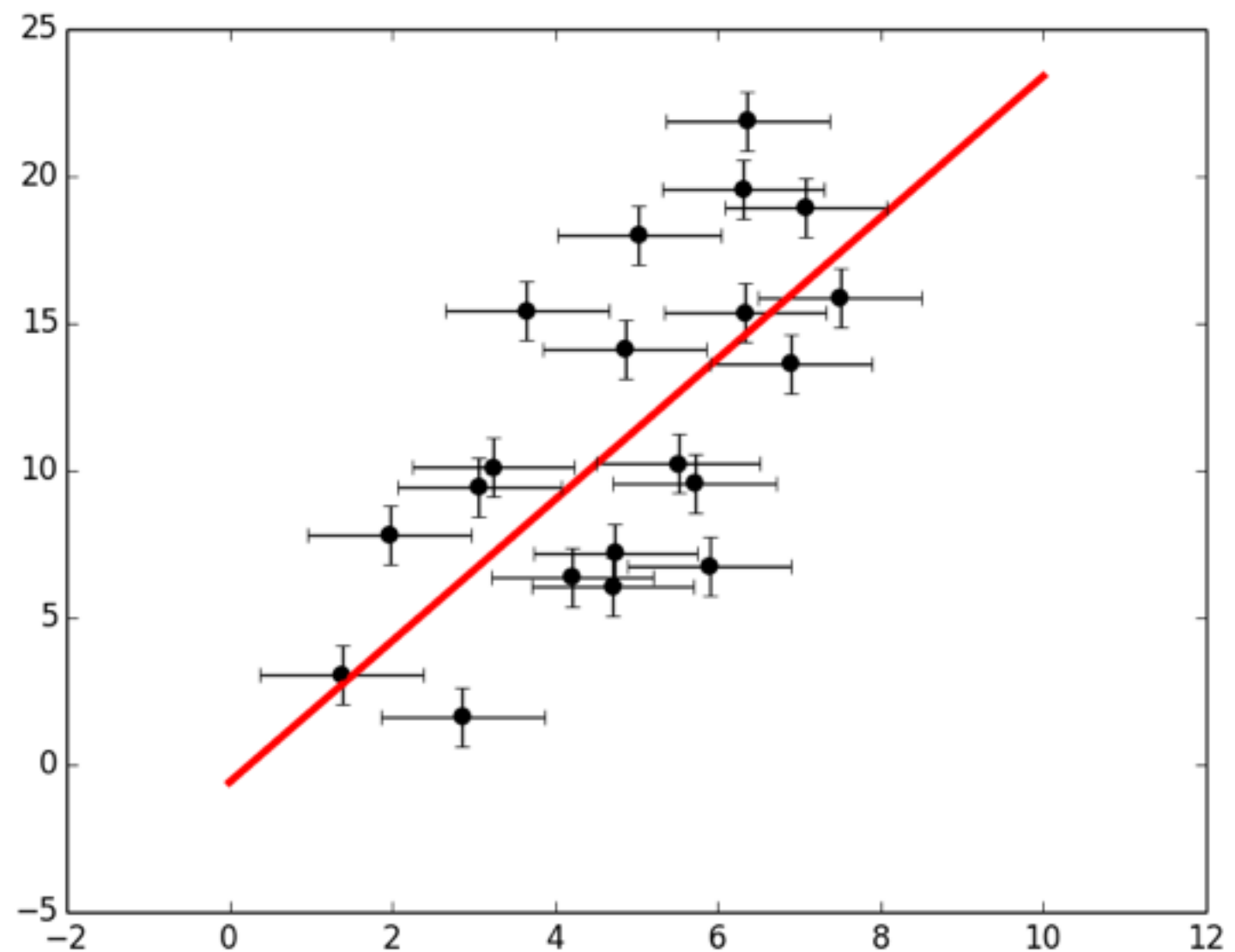
What you know after looking at the data =

what you knew before  
+ what the data told you



# Models & Parameters

- A model is the mathematical theory that describes how your data arose.
  - It is **not** a theory of how what you **wanted** to measure arose.
- Non-trivial models include some deterministic and some stochastic parts.
  - Noise is one stochastic; many (most?) astrophysical models also have others too

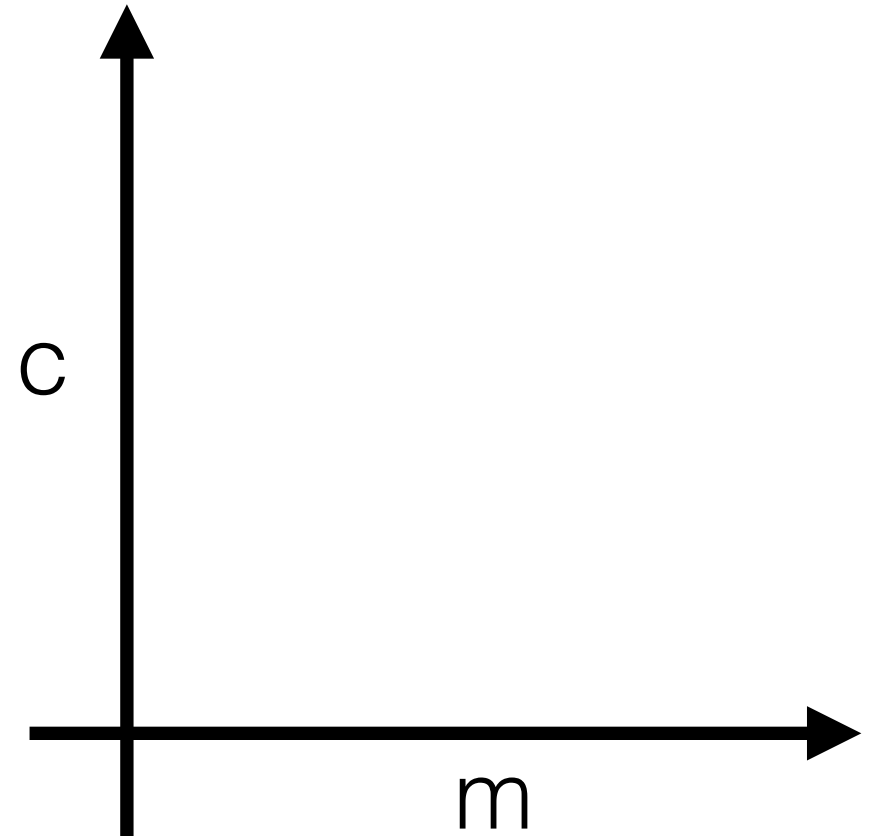


# Models & Parameters

- Parameters are any unknown numerical values in your model
  - A parameter can have probability distributions
- You need (and have) some prior (background) information about all your parameters
  - This may be subjective!

# Parameter Spaces

- Can use continuous parameters as dimensions in an abstract space
- Probabilities become functions of many variables:  
 $P(uvwxyz)$
- As the dimension of this space increases your intuition becomes worse



# Descriptive Statistics

- Reduce samples or distribution to set of characteristic numbers
  - In a analytic cases this is all you need to describe a distribution
- Statistics of samples  
= estimators/approximations to underlying distribution stats

# Descriptive Statistics:

## Mean

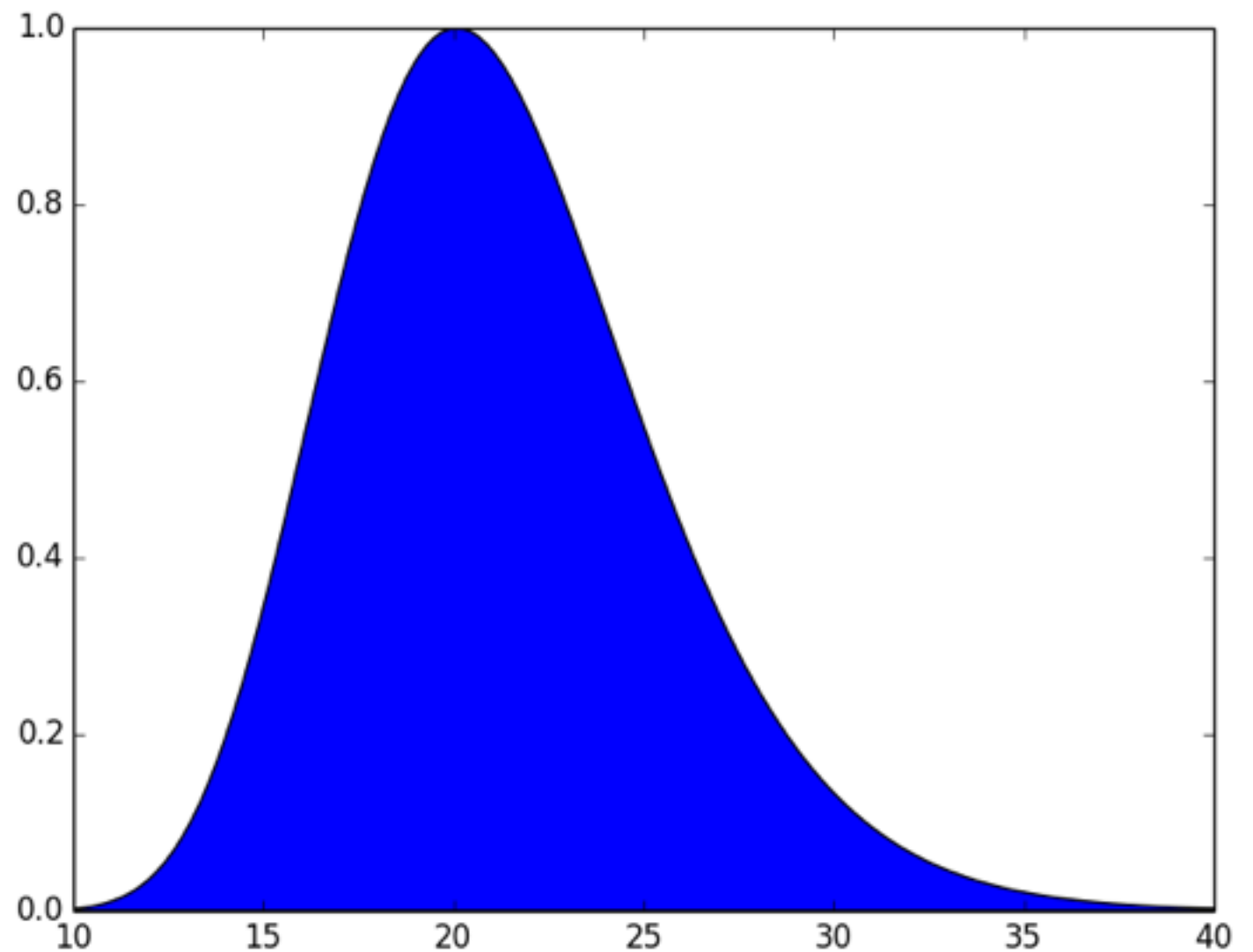
- Distribution mean
- Sample mean

$$E[X] = \int X P(X) dX$$

$$\bar{X} = \frac{\sum X_i}{N}$$

# Descriptive Statistics: Mean

- Means can be misleading!
- Most distributions are asymmetric



# Descriptive Statistics: Variance

- Distribution variance  $\text{Var}(X) = E[(X - \bar{X})^2]$   
$$= \int (X - \bar{X})^2 P(X) dX$$
- Sample variance 
$$\sigma_X^2 = \frac{\sum (X_i - \bar{X})^2}{N}$$
- Population variance 
$$s_X^2 = \frac{\sum (X_i - \bar{X})^2}{N - 1}$$

# Descriptive Statistics: Covariance

$$\begin{aligned}\text{Cov}(X, Y) &= E[(X - \bar{X})(Y - \bar{Y})] \\ &= \int (X - \bar{X})(Y - \bar{Y})P(XY)dXdY\end{aligned}$$

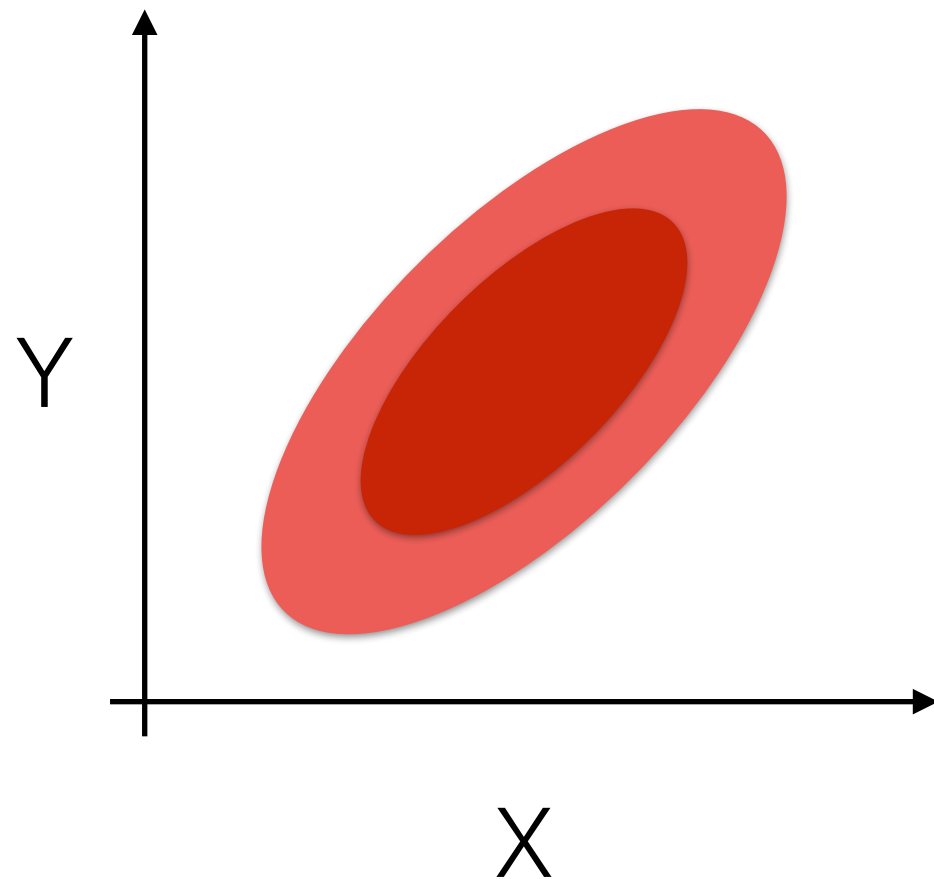
- Covariance

$$\sigma_{XY} = \frac{\sum (X_i - \bar{X})(Y_i - \bar{Y})}{N}$$

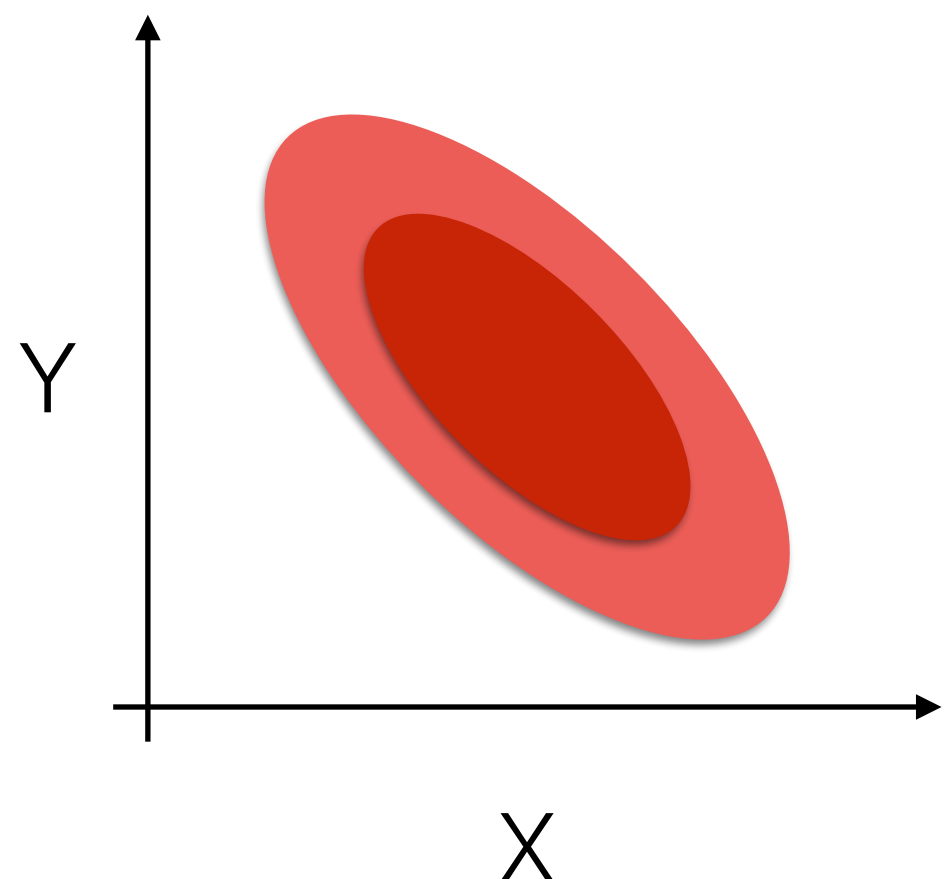


# Descriptive Statistics: Covariance

$$\sigma_{XY} > 0$$



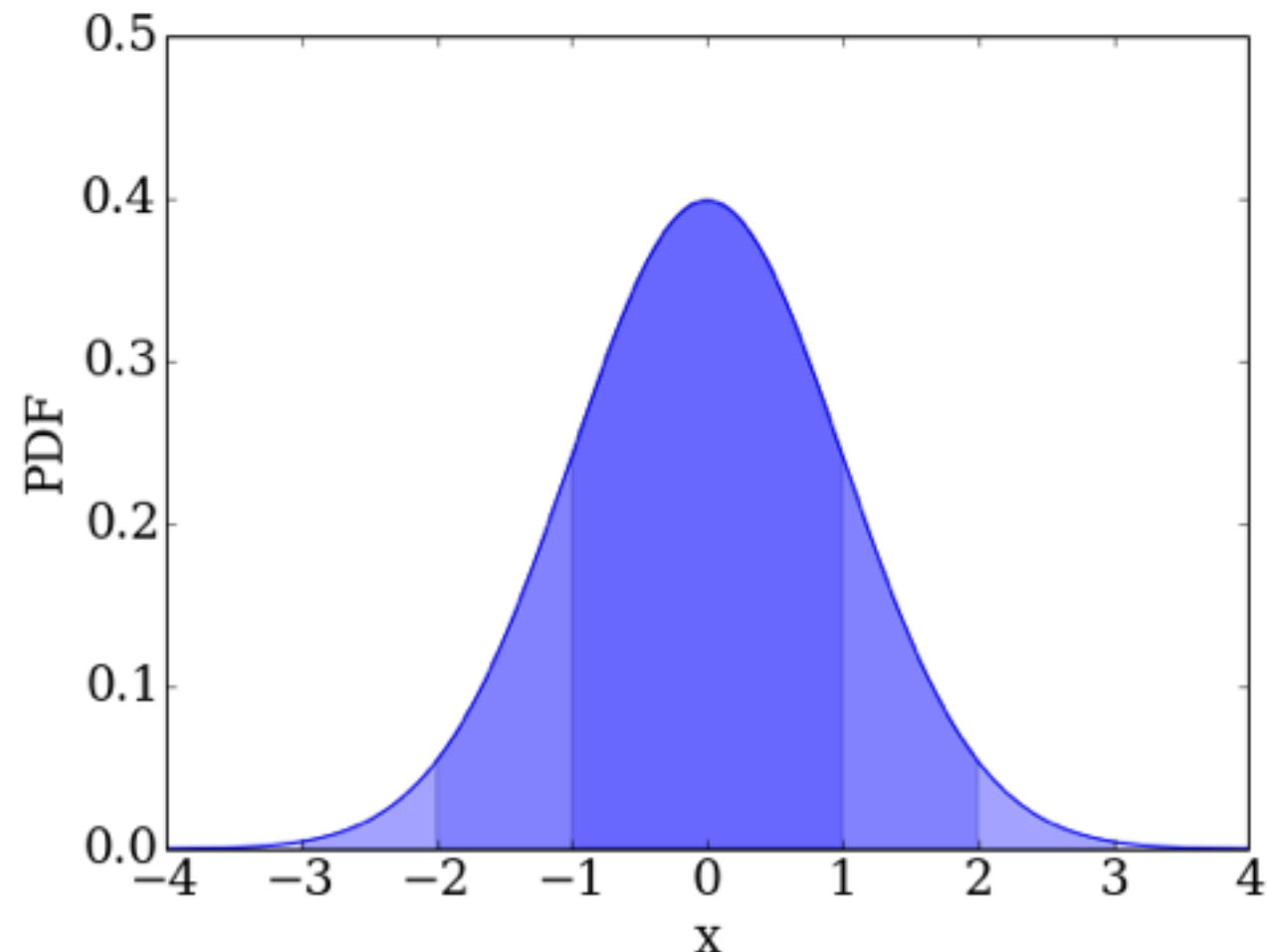
$$\sigma_{XY} < 0$$



# Gaussians: The Basics

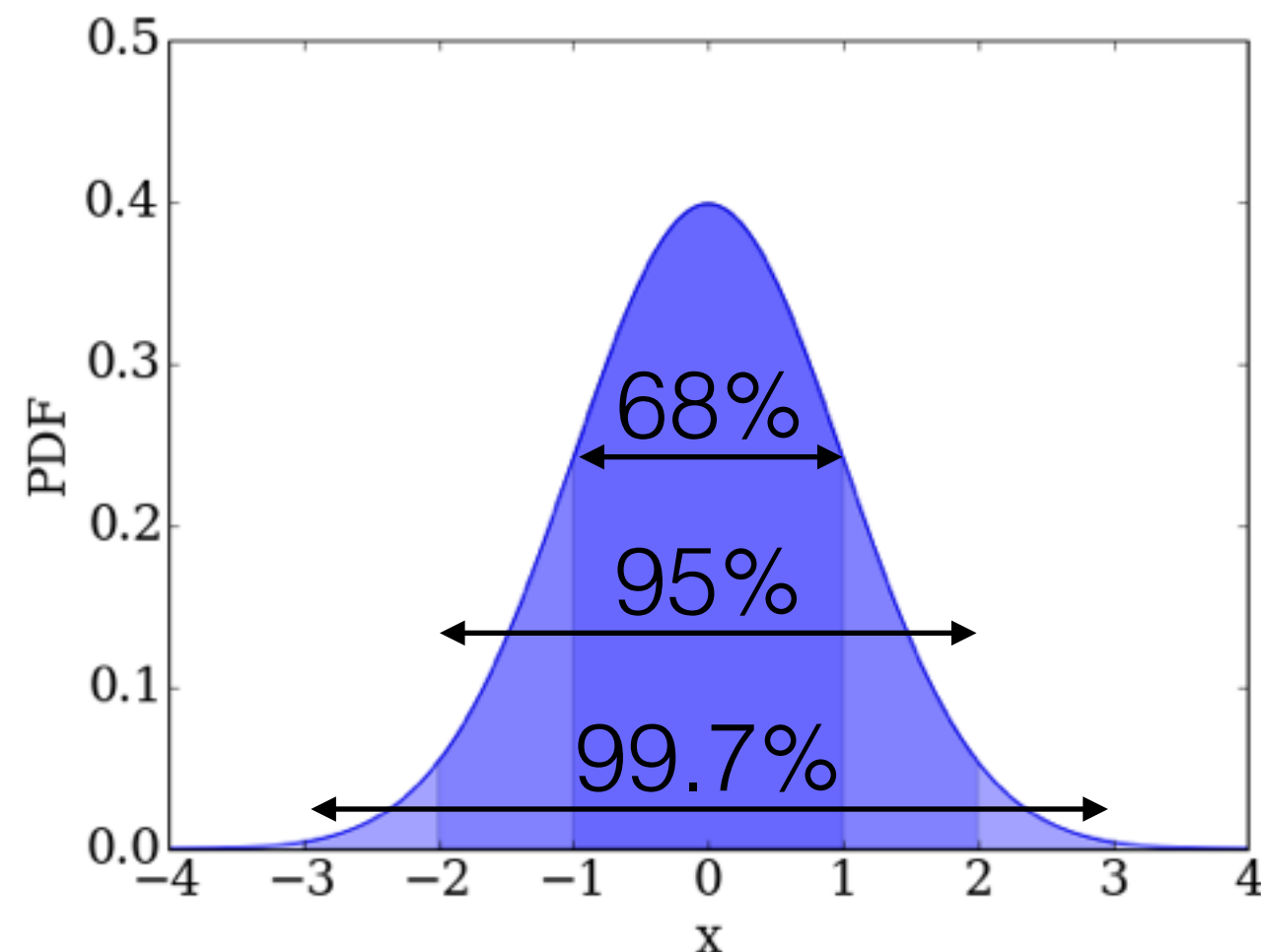
- One dimensional continuous PDF
- Two parameters:  
Mean  $\mu$   
Standard deviation  $\sigma$
- Symmetric
- Common! But often an over-simplification.

$$P(x; \mu, \sigma) = \frac{1}{\sqrt{2\pi}\sigma} \exp \left[ -\frac{(x - \mu)^2}{2\sigma^2} \right]$$



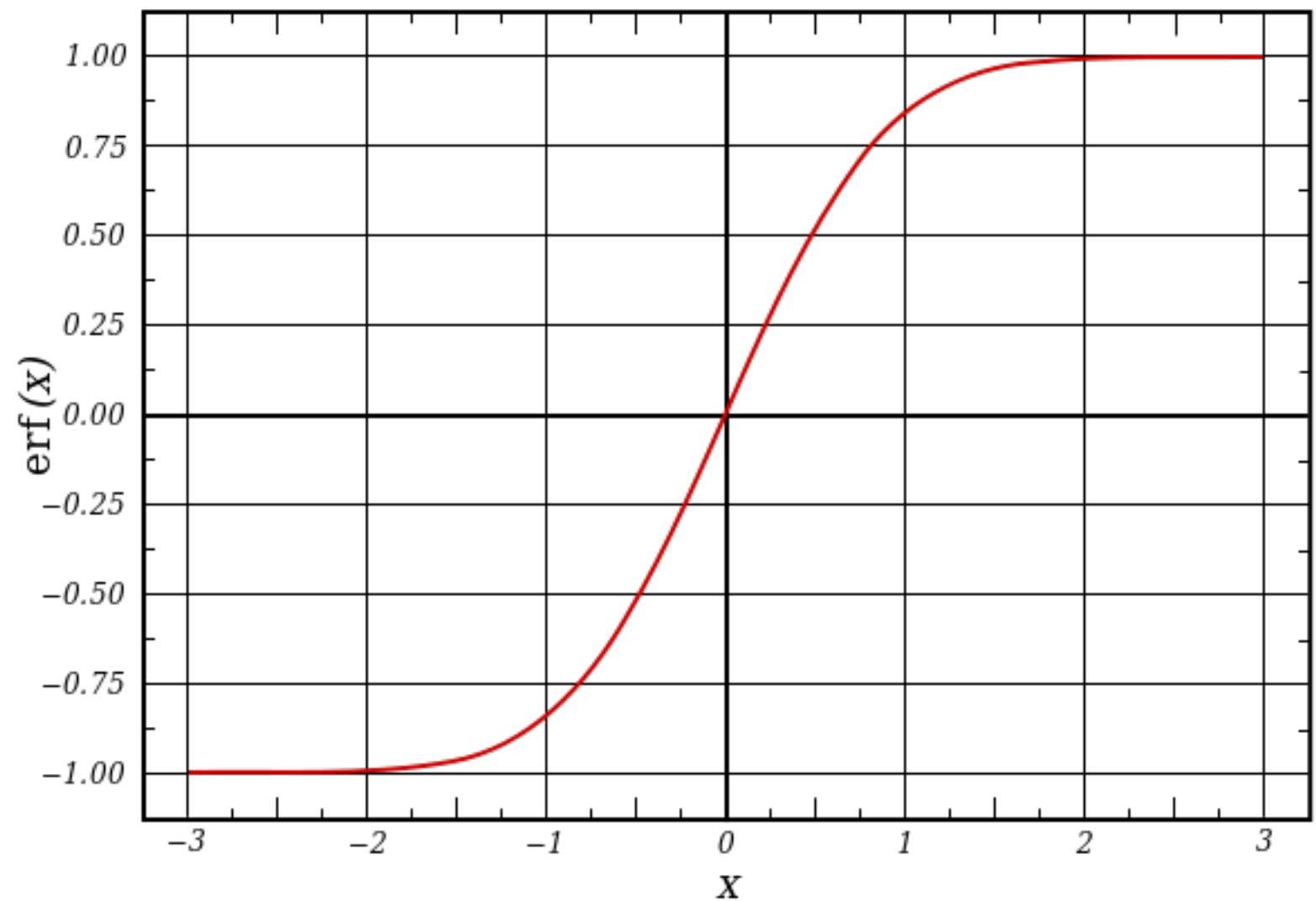
# Gaussians: Sigma numbers

- Distance from mean defined in number of standard deviations sigma
- Probability mass:
  - 68% within  $1\sigma$
  - 95% within  $2\sigma$
  - 99.7% within  $3\sigma$



# Gaussians: Properties

- **Error function** is cumulative integral of Gaussian
- Sigma numbers can be read off



# Gaussians: Properties

- Sum of Gaussians has simple form:

$$X \sim \mathcal{N}(\mu_x, \sigma_x^2)$$

$$Y \sim \mathcal{N}(\mu_y, \sigma_y^2)$$

$$\implies X + Y \sim \mathcal{N}(\mu_x + \mu_y, \sigma_x^2 + \sigma_y^2)$$

- Especially useful for sum of identical Gaussians, and leads to formula that error on the mean  $\sim n^{1/2}$

# Gaussians: Properties

- **Central limit theorem:**

Given a collection of random variables  $X_i$ :

$$\frac{1}{s_n} \sum_{i=1}^n (X_i - \mu_i) \rightarrow \mathcal{N}(0, 1)$$

$$s_n^2 = \sum_{i=1}^n \sigma_i^2$$

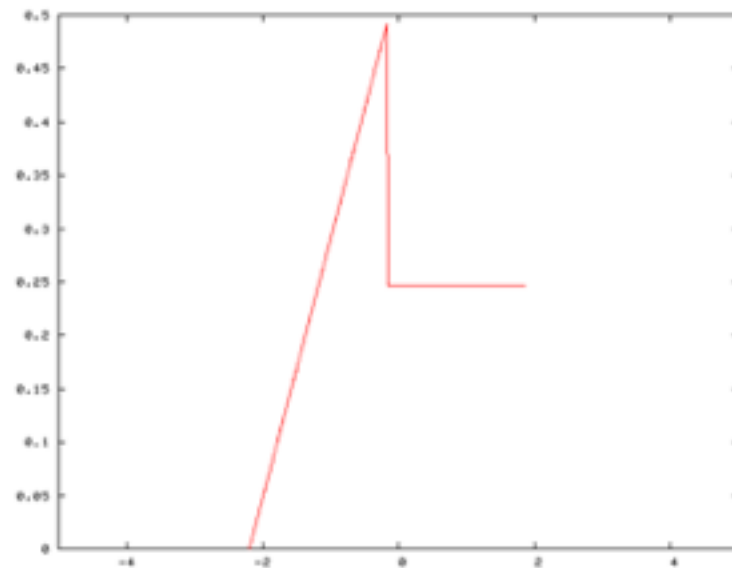
- Provided that:

$$\frac{1}{s_n^2} \sum E [(X - \mu_i)^2] \rightarrow 0$$

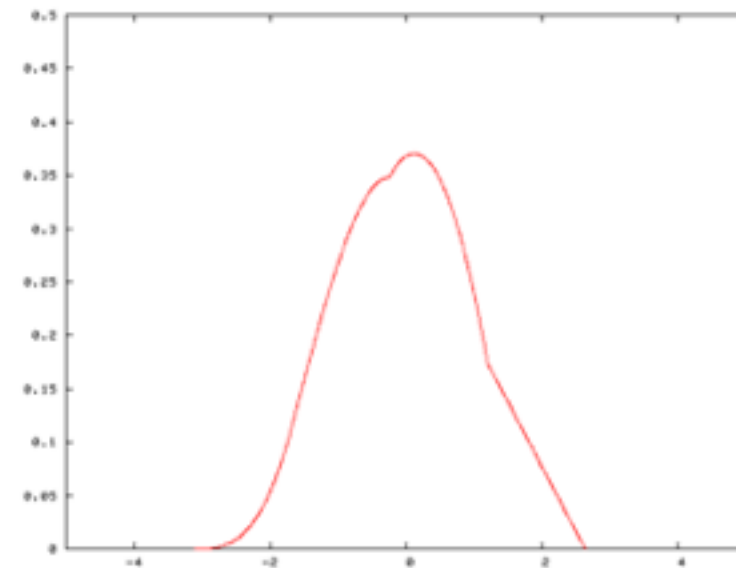
# Gaussians: Properties

- **Central limit theorem:**

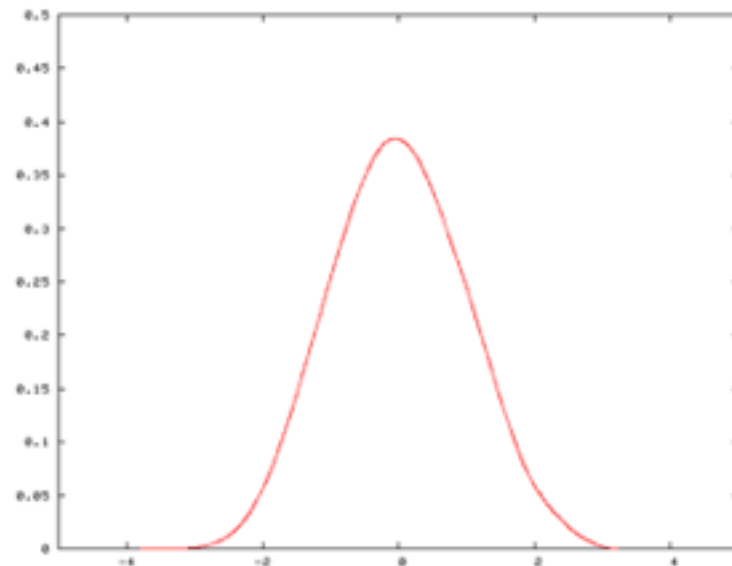
Single  
distribution



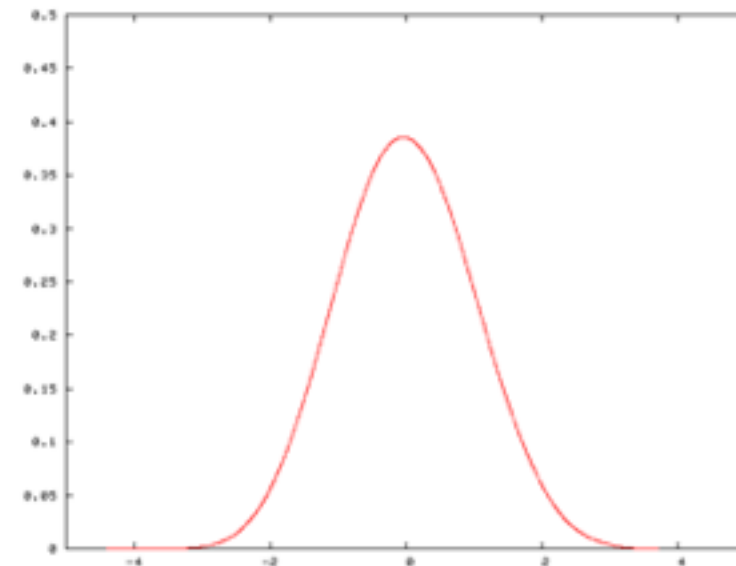
Mean of 2



Mean of 3



Mean of 4



# Gaussians: Multivariate

$$P(\underline{x}; \underline{\mu}, C) = \frac{1}{(2\pi)^{\frac{n}{2}} |C|} \exp \left[ -\frac{1}{2} (\underline{x} - \underline{\mu})^T C^{-1} (\underline{x} - \underline{\mu}) \right]$$

- C is the covariance matrix - describes correlations between quantities
  - For example: data points often have correlated errors



# Interpretations of Probability

	Frequentists	Bayesians
Use probabilities to ...	describe frequencies	quantify information
Think model parameters are ...	fixed unknowns	random variables with probabilities
Think data is ...	a repeatable random variable	observed and therefore fixed
Call their work ...	"Statistics"	"Inference"
Make statements about ...	intervals covering the truth x% of the time	constraints on model parameters
Have ...	many approaches with lots of implicit choices	one approach with explicit choices

# Why Bayesian probability for science?

- Answers the right question
  - We want facts about the world, not about hypothetical ensembles of experiments
- The ideal process is always clear
  - Practical implementations more difficult
- Problems and questions are more explicit

# Interpretations of Probability

- Frequentist approach:
  - Construct an estimator, a single number derived from your data points
  - Simulate data under different models and hypotheses and see how often measured estimator value appears

# Interpretations of Probability

- Bayesian approach:
  - Construct a probability of the parameters given the data
  - Compute that probability for various points in parameter space to see if they are good fits

# Interpretations of Probability

- Most astronomy data analysis takes neither of these approaches
  - Make up a statistic using rules of thumb and things you half remember from undergrad

# A few maxims

- Don't model your data.  
Model the process that led to your data.
- Everything is a distribution.  
Distrust point estimates.
- You can't learn anything without making assumptions.  
All probabilities are conditional.

# Easy Questions

- Show that if  $X$  is independent of  $Y$  then  $Y$  is independent of  $X$
- Linda is 31, single, outspoken, and very bright. She majored in philosophy in college. As a student, she was deeply concerned with racial discrimination and other social issues, and participated in anti-nuclear demonstrations. Estimate the probability of these things being true:
  - (1) Linda is active in the feminist movement.
  - (2) Linda is a bank teller.
  - (3) Linda is a bank teller and active in the feminist movement.
- Show that  $P(XY) \leq P(X)$  and  $P(XY) \leq P(Y)$
- If a roll a twenty-sided dice and cube the number shown, what is the expectation of the result?

# Medium Question

- Photons arrive at a detector with a Poisson distribution with  $\lambda = 1$  photon/s

Each photon has an energy drawn from a Gaussian distribution with  $\mu = 1000$  eV and  $\sigma = 100$  eV.

Plot the probability distribution of the amount of energy arriving per second.

The energy of each photon is independent of the number that arrive.



# Hard Question

- On my journey to work I can see the bus stop for the last 3 minutes of my walk towards it.

On my first day I saw one bus go past it before I got there. How long did I think I would have to wait for the next bus?

- You can assume that buses obey Poisson statistics. This is reasonable for British buses.
- If you need to make any other assumptions then describe and justify them.